

Introduction to Holomorphic Dynamics

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$$f_c(z) := z^2 + c$$

QUADRATIC FAMILY

$c \in \mathbb{C} \setminus \mathbb{R}$ LOGISTIC

$$f_c: \hat{\mathbb{C}} \rightarrow \hat{\mathbb{C}}$$

$$g_a(x) = a \times (1 - x)$$

a = parameter

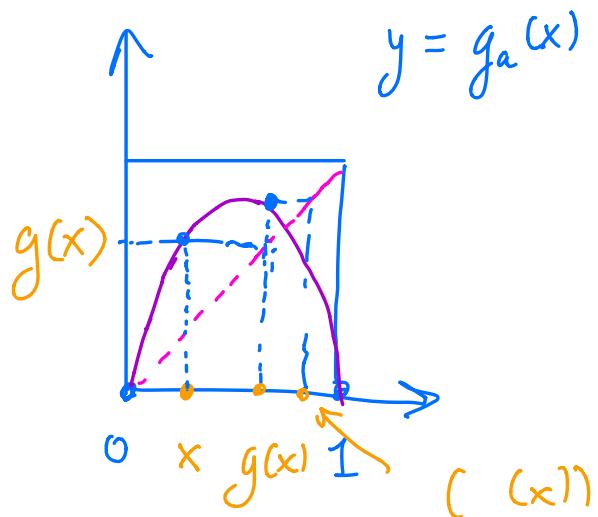
$$x \in [0, 1]$$

$x \in [0, 1]$ "initial condition"

$g_a(x)$ "state of system after
1 unit of time"

$g_a(g_a(x))$... 2 units of time

$g_a(g_a(g_a(x)))$... 3 units...



Def: A ^(DISCRETE-TIME) DYNAMICAL SYSTEM is a pair (X, T) , where X is a ... space and $T: X \rightarrow X$ is a map from X to itself.

Def: $(x, T(x), T(T(x)), \dots, \overbrace{T \circ \dots \circ T}^n(x), \dots)$ is the ORBIT of x under g

$$T^n(x) := \underbrace{T \circ T \circ \dots \circ T}_n(x) \quad \text{ n^{th} iterate}$$

E.g.: ① TOPOLOGICAL DYNAMICS

X = topological space
(compact?)

$T: X \xrightarrow{\hookrightarrow}$ continuous.

② MEASURABLE DYNAMICS

(X, \mathcal{A}, μ) = measure space

$T: X^G$ measure-preserving

$$(T_*\mu = \mu)$$

$$T_*\mu(A) = \mu(T^{-1}A)$$

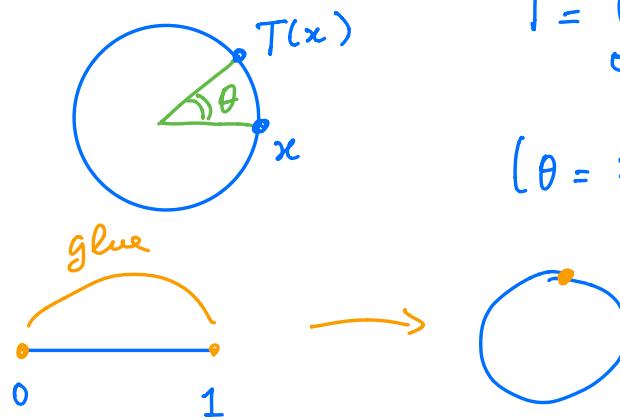
③ HOLOMORPHIC DYNAMICS

X = complex manifold (\mathbb{C})

$T: X^G$ holomorphic map.

Basic Examples

① Rotations



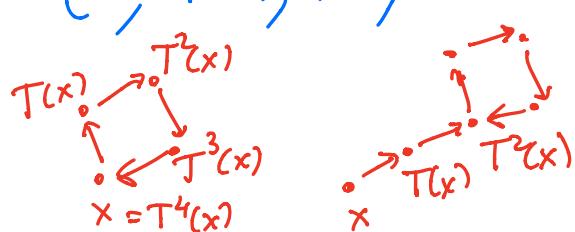
$X = S^1 \cong \mathbb{R}/\mathbb{Z}$
 $T = \text{Rotation of angle } \theta$
 $(\theta = 2\pi \alpha)$

$$X = \mathbb{R}/\mathbb{Z}$$

$$T(x) = x + \alpha \pmod{1}$$

Denote $\mathcal{O}_T(x) = (x, T(x), \dots, T^n(x) \dots)$

$$\alpha = \frac{1}{5}$$



$$\mathcal{O}_T(x) = \left(x, x + \frac{1}{5}, x + \frac{2}{5}, x + \frac{3}{5}, x + \frac{4}{5}, x + 1 \right)$$

Dif.: x is periodic for T if x

$\mathcal{O}_T(x)$ is finite. It is
purely periodic if $\exists n \geq 1$ s.t. $T^n(x) = x$ and
eventually periodic otherwise

Note : the behaviour of $\theta_T(x)$ is the same for all x .

E.g.: $\alpha = \frac{p}{q}$, $(p, q) = 1$

Then every x is periodic of period q .

What if $\alpha \in \mathbb{R} \setminus \mathbb{Q}$?

No x is periodic.

Proof if $T^n(x) = T^m(x)$

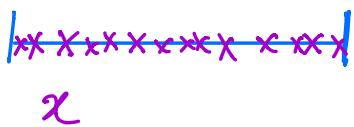
for $n > m$

$$x + n\alpha = x + m\alpha \pmod{1}$$

$$(n-m)\alpha = 0 \pmod{1}$$

$\Rightarrow \alpha \in \mathbb{Q} \Rightarrow$ contradiction

Prop.: if $\alpha \in \mathbb{R} \setminus \mathbb{Q}$, then for any x in $[0, 1)$, $\Theta_{T_\alpha}(x)$ is DENSE in $[0, 1)$.



FACT The orbit of x is EQUIDISTRIBUTED along $[0, 1)$.

Rotation of irrational angle is a QUASIPERIODIC system.

Example 2

Doubling Map

$$T(x) = 2x \pmod{1}$$

$$T: \mathbb{R}/\mathbb{Z} \rightarrow \mathbb{R}/\mathbb{Z}$$

PERIODIC POINTS for T

$$\frac{1}{2^n} \rightarrow \frac{1}{2^{n-1}} \rightarrow \dots \rightarrow \frac{1}{2} \rightarrow 0^{\textcircled{5}}$$

$$\frac{1}{3} \rightarrow \frac{2}{3} \rightarrow \frac{4}{3} = \frac{1}{3}$$

purely
periodic
period 2

$$\frac{1}{5} \rightarrow \frac{2}{5} \rightarrow \frac{4}{5} \rightarrow \frac{3}{5} \rightarrow \frac{1}{5} \quad \underline{\text{period 4}}$$

$$2^4 - 1 = 15 = 5 \cdot 3$$

period 3

$$\frac{1}{7} \rightarrow \frac{2}{7} \rightarrow \frac{4}{7} \rightarrow \frac{1}{7}$$

$$7 = 2^3 - 1$$

Fact Periodic Points for the doubling map are precisely the rationals.

$$\text{Pf.: } T^n(x) \approx T^m(x) \quad n > m$$

$$2^n x + p = 2^m x + q$$

$$(p, q \in \mathbb{Z})$$

$$(2^n - 2^m)x = q - p$$

$$x = \frac{q-p}{2^m(2^{n-m} - 1)}$$

x purely periodic ($\underline{m=0}$)

$$x = \frac{q-p}{2^n - 1}$$

\boxed{Q} is $\frac{3}{14}$ purely periodic
or eventually periodic.

$$\frac{3}{14} \rightarrow \frac{3}{7} \rightarrow \frac{6}{7} \rightarrow \frac{5}{7}$$

$x \in \mathbb{Q} \implies x \text{ periodic}$

$$x = \frac{p}{q} \implies T^n(x) = \frac{2^n p}{q} + \frac{k}{q} = \frac{2^n p + kq}{q}$$

The orbit of x is contained in the finite set $\left\{ \frac{k}{q}, k \in \mathbb{Z} \right\}$.

Fact A rational $x \in \mathbb{Q}$

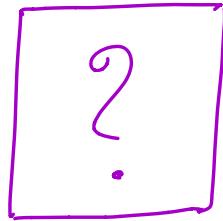
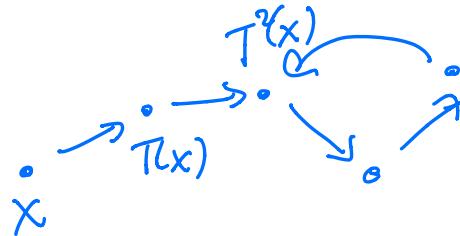
is purely periodic for doubling map iff its denominator is ODD.

Proof x purely periodic

then $x = \frac{k}{2^n - 1} \implies \text{den}(x)$
is odd since it divides $2^n - 1$

$$x = \frac{P}{q} , q \text{ odd}$$

$\Rightarrow x$ purely periodic.



Cor.: ① periodic points are dense
 ② there are points with dense orbit

[Q] Example of $x \in [0, 1)$
 with dense orbit for $T(x) = 2x \pmod{1}$

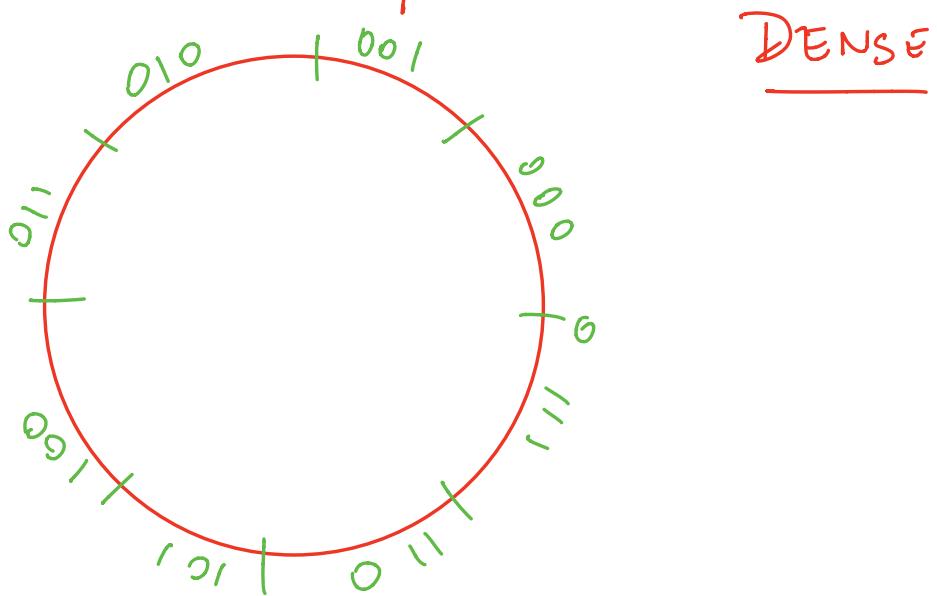
$$x = .b_1 b_2 b_3 \dots b_n \dots \quad (\text{base 2})$$

$$T(x) = .b_2 b_3 \dots b_n \dots$$

T acts as shift \rightarrow

$$x = .01000110110001\dots$$

Given any finite sequence, there is n s.t. $T^n(x)$ starts with that sequence. \Rightarrow orbit is



Def.: T is TOPOLOGICALLY TRANSITIVE if there exists x with dense orbit. T is MINIMAL if EVERY point has dense orbit.

DOUBLING
MAP

- ① TOP. TRANSITIVE
(not MINIMAL)
- ② periodic pts are dense

It is an example of a
HYPERBOLIC / EXPANDING / CHAOTIC

IRRATIONAL
ROTATION

① MINIMAL

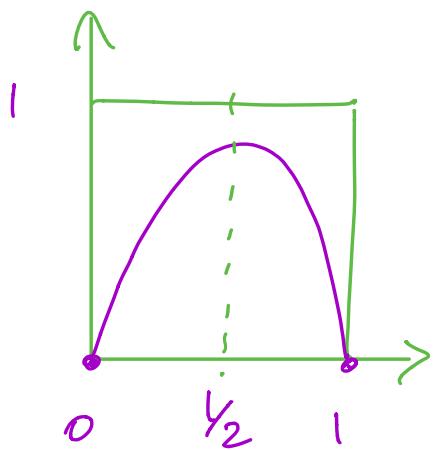
QUASIPERIODIC

DYNAMICS IN ONE REAL VARIABLE

$$g_a(x) = a \cdot x \cdot (1-x) = ax - ax^2$$

$a \in \mathbb{R}$ parameter

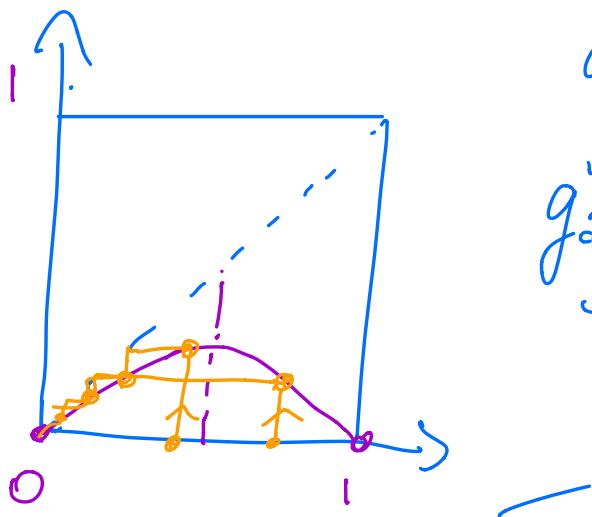
$$g_a : [0, 1] \rightarrow [0, 1]$$



$$g_a\left(\frac{1}{2}\right) \leq 1$$

$$a \cdot \frac{1}{2} \cdot \frac{1}{2} \leq 1$$

$$\boxed{0 \leq a \leq 4}$$



a small :

$$g_a^n(x) \rightarrow 0$$

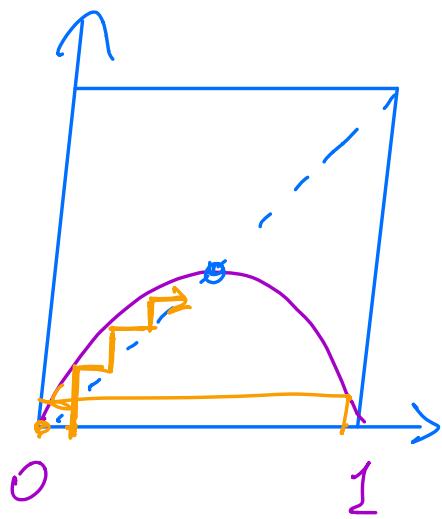
for any x

$$g'_2(0) \leq 1$$

$$g'_2(x) = a - 2x^a$$

$$g'_2(0) = \underline{a \leq 1}$$

$$\underline{a = 2}$$



$$g_2\left(\frac{1}{2}\right) = \frac{2}{4}$$

$$g_2\left(\frac{1}{2}\right) = \frac{1}{2}$$

$$1 < a \leq 2$$

For every x , $g_a^n(x) \rightarrow x_0 \neq 0$
 which is
 an attracting
 fixed point.

Def.: x is FIXED POINT if

$$T(x) = x.$$

x is an ATTRACTING F.P. if

$$|T'(x)| < 1$$

x is a REPELLING F.P. if

$$|T'(x)| > 1.$$

In the logistic family

$$g_\alpha(x), \quad \text{for } \alpha \leq 1, \quad g_\alpha^n \rightarrow 0$$

$$1 + \varepsilon > \alpha > 1, \quad g_\alpha^n \rightarrow x_0 \neq 0$$

Def.: $\underline{\alpha = 1}$ is a BIFURCATION PARAMETER

$$\begin{cases} g_\alpha(x) = \alpha x - \alpha x^2 = x \\ g'_\alpha(x) = 1 - 2\alpha x \end{cases}$$

$$x \neq 2 \quad 2 - 2x = 1$$

$$x = \frac{2-1}{2}$$

$$\begin{aligned}g_2'(x) &= 2 - 2 \cancel{\frac{2-1}{2}} = \\&= 2 - 2a + 2 = |2-2a| < 1\end{aligned}$$

$$|2-a| < 1 \implies \boxed{1 < a < 3}$$

For $1 < a < 3$, there
is a non-zero attracting
fixed point.

GOAL OF CLASS

- [1] Classification of all local dynamical behaviour for $f_c(z) = z^2 + c$
- [2] Describing combinatorially Julia & Mandelbrot set
- [3] Applications to Entropy.
- using entropies to classify complex polynomials